Digital PID Controller

BGK81/BGK84/BGK85/BGK87/BGK89 **INSTRUCTION MANUAL**

BGK80B-E1

Carefully readall the instructions in this manual. Please place this manualin a convenient location for easy reference.



- An external protection device must be installed iffailure of this instrument could result in damage to the instrument, equipment or injury topersonnel
- All wiring must be completed before power in turned on to prevent electric shock, fire or damage to instrument and equipment .
- This instrument must be used in accordance with the specifications to prevent fire or damage to instrument and equipment.
- This instrument is not intended for use in locations subject to flammable or explosive gases.
- Do not touch high-voltage connections such as power supply terminals . etc. to avoid electric shock.



- . This instrument is protected from electric shockby reinforced insulation. Provide reinforced insulation between the wirefor the input signal and the wires for instrument power supply, source of power and loads.
- This instrument is design for installation in an enclosed instrumentation panel. All high-voltage connections such as power supply terminals must be enclosed in the instrumentation panel to avoid electric shock by operating personnel.
- · All precautions described in this manual should be taken to avoid damage to the instrument or equipment.
- All wiring must be in accordance with local codes and regulations.
- described in this manual. Always observe precautions Otherwise serious injury or accident may result.
- . Do not allow metal fragments or lead wire scraps to fall inside this instrument. This may cause electric shock, fire or malfunction.
- Firmly tighten each terminal screw at the specified torque. Otherwise electric shock or fire may result.
- Do not place any obstacle around this instrument in order not to impede radiation of heat. And do not close ventilation holes.
- · Do not connect wires to unused terminals.
- . Before cleaning the instrument, always turn off the power supply.
- Remove stains from this instrument using a soft, dry cloth. Do not use a volatile solvent such as thinner in order to avoid deformation or discoloration.
- Do not rub nor strike the display unit of this instrument with a hard object.

1. PRODUCT CHECK

BGK81 (Size:48x48mm) BGK84 (Size:48x96mm) BGK85 (Size:96x48mm) BGK87 (Size:72x72mm) BGK89 (Size:96x96mm)

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(1) (2)	(3)	(4) (5)	(6)(7)	(8)

(1) Control action

() • • • • • • • • • • • • • • • • • •					
F: PID reverseaction with	autotuning N: No control				
(2) Input type,(3) Range code:	See"8.INPUTRANGE TABLE"				
(4) Control output[OUT]: N: N	lo control output				
M:Relay contact	V: Voltagepulse				
8: Current(DC4 ~20 mA)	5:DC0-5VDC				
6: DC0-10VDC	T: Trigger (for triac driving)				
(5) Remark: N:No					
(6) Alarm1[AL1 for highalarm]	See"5.5 Initial Setting "				
N: No alarm					
A: Deviationhigh alarm	H: Process high alarm				
B: Low deviation alarm	J: Processlow alarm				
(7) Alarm2[AL2 for lowalarm]	See"5.5 Initial Setting "				
N: No alarm					
A: Deviation high alarm	H: Process high alarm				
B: Low deviation alarm	J: Processlow alarm				
(8) Power					
A: 220VAC B: 85-265V/	AC D: 24VDC E: 24VAC				
<pre></pre>					
Model:BGK89	Specification: Model of the controller: BGK89				
Code: FKA4-MN*AN-B	Size: 96mm x96mm				
	Control action: PID reverse action				
is very important when ordering.	Out put: Relayoutput				
	Power: AC85-265V				

2. MOUNTING

2.1 Mounting Cautions (1) Use this Instrument withi

- within the following ambient temperature and ambient humidity
- Allowable ambient temperature: 0 to 50°C
- Allowable ambienthumidity: 45 to 85% RH
- (2) Avoid the following when selecting the mounting location. • Rapid changes in ambient temperature which may cause condensation.
- Corrosive or inflammable gases.
- Direct vibration or shock to the mainframe.
- ·Water,oil,chemicals,vaporor steam splashes.
- •Excessive induction noise, static electricity, magnetic fields or noise.
- •Direct air flow from an air conditioner.

 Exposure to direct sunlight Excessive heat accumulation.





3.1 Wiring cautions

(1) For thermocouple input, use the specified compensation wire.

- (2) For RTD input, use leads with low resistance and having no resistance differences among the 3 leads.
- (3) Conduct inputsignal wiring away from instrument power, electric equipment power and load lines to avoid noise induction.
- (4) Conduct instrument power wiring so as not tobe influenced by noise from the electric equipment power. If the instrument may be affected by external noise, a noise filter should be used. Twist these leadwires

instrument power

pitches

IN

Shorten distance between

Noise filter

OUT

Minimize

distance

- * Shorten the distance between twisted power supply wire pitches. The shorter the distance between the pitches, the more effective for noise reduction.
- * Install the noise filter on the panel which is always grounded and minimize the wiring distance between the noise filter output side and the instrument power terminals.
- * Do not install fuses and/or switches on the filter output signal since this may lessen filter effect.
- (5) For wiring, use wires conforming to the domestic standard of each country.
- (6) Abot4 to 5 seconds are required as the preparation time for contact output after poweron. Use a delay relay when the output line is used for an external interlock circuit.
- (7) This instrumenthas no power supply switch norfuses. Therefore, install the fuse close to the instrument and the switch, if required. *Recommended fuse rating: Rated voltage; 250V Rated current; 1A * Fuse type; Time-lag fuse
- (8) Do not excessively tighten the terminal screws. In addition, use the solderless terminal appropriate to the screw size.
- (9) To the instrument with power supply of 24V, please besure to supply the power from SELV circuit.

3.2 Terminal Configuration

CAUTION

(1)All the underhookups are only for reference. (2)For wiring, please according to the hookup label which was glued on the plastic case of controller.



Power supply voltage:

7VAmax(at 100VAC)

Alarm outut rated:

Control output rated :

AC220V±10% (Frequency: 50/60Hz, Rating: 200~240VAc) 22 to 26 V AC (Frequency: 50/60Hz, Rating: 24VAC) 22 to 26V DC (Rating: 24V Dc) Power consumption: 5VA max (at 24V AC) 160mA max (at 24V DC)

Relay contact output: 250V AC, 3A (Resistive load)

Relay contact output: 250V AC,3A(Resistive load)

Trigger output(for triac driving):100A or less

Voltage pulse output: 0/12 V DC (Load resistance 600 Ω or more) Current output: 4 to 20mA DC (Load resistance 500 Ω or less)

10VA max(at 240V AC)





Instrument

. terminals

power

4. PARTS DESCRIPTION



5. SETTING

5.1 Calling up procedure of each mode

*1. Input type and input range display



5.2 Setting set value(SV) Example: Following is an example of set value(SV) to 200°C



5.3 Setting parameters other than set value (SV)

The setting procedures are the same as those of example (2) to (4) in the above "Setting setvalue (SV)". Press the SET key after the setting end shifts to the next parameter. When no parameter setting is required, return the instrument to the PV/SV display mode.

5.4 PID level (Parameter List)

Press the "SET "key for 3 seconds to PIDIevel:

After the valuebe registered ,you can press "SET"key for 3 seconds to return the instrument to the PV/SV display mode.

(F)	
agsik	BGK89

The following parameter symbols are displayed one by one every time the SET key is pressed.

#1:	Factory	setvalue

Symbol	Symbol Name Setting range		Description	#1				
RL /	Alarm1set value (AL1)Deviation or Process alarm, -1999 to 9999		Set the alarm1 set value . Alarm differential gap=HYS,when P≠0	10				
Alarm2 set value (AL2) Deviation or Process alarm, -1999 to 9999		Set the alarm2set value . Alarm differential gap=HYS,when P 0	200					
50	PV bias	-1999 to +9999	Sensor correction is made by addingbias value to measured value(PV).	0.0				
HY5	Differential gap for alarm or output	0 to 9999	Out differential gap=HYS,whenP=0 (ON/OFF action) Alarm differential gap=HYS,whenP≠0(PID action)	0				
E	Continued on the next							

Continued on the next page

Symbol	Symbol Name Setting range		Description	#1
P	Proportional band	0.0~999.9	ON/OFF control if set to 0 (0.0) ON/OFF action differential gap=HYS	20.0
1	Integral time	0~3600 seconds	Set the time of integral action to eliminate the offset occurring in proportional control.	150
ď	Derivative time	0.0~999.9 seconds	Set the time of derivative action to improve control stability by preparing for output changes.	30.0
/	Proportioning cycle	1.0~200.0 seconds	Relay contact output:20S Voltage pulse(for SSR) :2S	20.0 or 2.0
RĿ	Auto tuning (At)	0:AT end or cancel 1:AT start or execution	Use AT function to automatically calculate and set the optimize PID value for your system. Turns the autotuning ON/OFF	0
LEĽ	Set data lock (LCK)	0: All parameters can be changed 1: Only SV can be changed 2: No parameters can be changed	Performs set data change enable/disable.	0

5.5 Initial Setting (Parameter List)



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#1. Factory set value

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After the value be registered, when no parameter setting is required, Press the SET key for 3s to return the instrument to the normal display. The following parameter symbols are displayed one by one every time the SET key is pressed.

		#1: Faci	ory set value
Symbol	Name	Description	#1
l nPE	Main input typeselect (InPt)	Input type selection as:thermocouple(TC),RTD,etc. See **A "INPUT TYPE SYMBOL TABLE"	К
RLdl	Alarm1 type selection (ALd1)	Select the type of alarm1 range:0~4 See ** B "ALARM TYPE TABLE"	2
RLd2	Alarm2 type selection (Ald2)	Select the type of alarm2 range:0~4 See ** B "ALARM TYPE TABLE"	0
LSPL	Low setting limiter (LSPL)	Set lower point within input see 14. chapter "INPUT RANGE TABLE"	0
USPL	Up setting limiter (USPL)	Set higher pointwithin input see 14. chapter "INPUT RANGE TABLE"	400
r E	Proportional reset (rE)	Overshooting restricted by the proportional effect.	10
SOFE	PV follow-up (SOFT)	PV variable-value control, (Setting range: 0 to 10) PV will response slower if SOFT is bigger.	2
ŪFF	Overshooting turn off (OFF)	Output forced turning off when the PV value overshooting . (Setting range: 0 to 100)	3
PRL	Lowest value of PV display (PAL)	Lowest value display when analog signal inputs, Such as 4-20mA input. The value of PV display when input 4 mA. Only for standard analog signal input.	0
PRH	Highest value of PV display (PAH)	Highest value display when analog signal inputs, Such as 4-20mA input. The value of PV display when input 20 mA. Only for standard analog signal input.	5000
d,P	Decimal point (dP)	Only for standardanalog signal input(current or voltageinputs). Range:0~3	0
	Output manipulated variable lowest limit (OTL)	Output manipulated variable lowest limit . Range : 0 to 100%	0
ОГН	Output manipulated variable highest limit (OTH)	Output manipulated variable highest limit . Range : 0 to 100%	100

**A: INPUT TYPE SYMBOL TABLE

InPt Setting	Ľ		Ε	5	Г	Ь	<i>,</i> –	ΡΓ	<u> </u>	U2
Input type	К	J	E	S	Т	В	R	Pt100	DC0-10V,(**DC 0-20mA)	DC2-10V,(**DC 4-20mA)
Range	-50 to1350° C	-50 to1000° C	-50 to1000° C	-50 to 1750° C	-20 to400° C	50 to1800° C	-20 to1750° C	-199.9 to600.0° C	-1999 to9999	-1999 to9999

1**,All input change in the above groups is possible by keyboard. For BGK81-N, BGK84-N, BGK85-N, BGK87-N, BGK89-N, only

CODE	RLdi	Alarm1 mode specification	CODE	RLd2	Alarm2 mode specification			
N	0	No Alarm	N	0	No Alarm			
	2	AL1>0 LOW SV Alarm ON HIGH			AL2≥0 LOW SV Alarm ON HIGH SV SV+AL2			
A		AL1<0 LOW Alarm ON LOW SV+AL1 SV HIGH	A	2	AL2<0 LOW Alarm ON LOW SV+AL2 SV HIGH			
В	4	AL1 > 0 Low deviation alarm	в	4	AL2 >0 LOW SV-AL2 SV			
		AL1<0 LOW SV AL1 HIGH			AL2<0			
н	1	Process high alarm iHrs Alarm ON LOW ▲AL1 HIGH	н	1	Process high alarm iHYS Alarm ON LOW AL2 HIGH			
J	3	Process low alarm Alarm ON HYS LOW AL1 HIGH HIGH (formatic lange HIVO where PC0/(PIP partice)	J	3	Process low alarm Alarm ON HYSE LOW LOW Al2Value HIGH			

thermocouple and Pt100 can be changedby key board. 2**,For the current input (0-20mA or 4-20mA) specification, a resistor of 500^Ω must be connected between the input terminals. ****B: ALARM TYPE TABLE** ▲:SV △:Alarm set value \blacktriangle :SV \triangle :Alarm set value

PID AUTOTUNING (AT) FUNCTION 6.

Autotuning (AT) start

- 1) Press the "SET" key for 3 seconds to PID level.
- 2) Looking for the parameter "AT ".
 3) Set "AT" value from 0 to 1.

- 4) Press the "SET" key start auto tuning.
 5) Press the "SET" key for 3 seconds to return to the instrument to the PV/SV displaymode.

(If AT be started , the AT lamp will be lighted on and the lamp is flashing) PV 🖌



Autotuning (AT) automatically measures, calculates and sets the optimum PID. The following conditions are necessary to carry out autotuning and the conditions which will cause the autotuning to stop.

Caution for using the Autotuning (AT)

When a temperature change (UP and/or Down) is 1 ${}^\circ\!\mathrm{C}$ or less per minute during Autotuning, Autotuning may be cancelled before calculating PID values. In that case, adjust the PID

7.ERROR DISPLAYS

Error display

Turn off the power once. If an error occurs RAM failure(Incorrect set date write or check sensor and after the power is turned on again, please sensor connection, etc.) contact sales office or the agent. [Flashing] Overscale and Underscale Measured value(PV) PV is outside of input range WARNING [Flashing] Overscale: Toprevent electric shock, always turn ドドド off the power before replacing the PV is above the high input display range limit. sensor. [Flashing] Underscale: Check input type, input range, sensor PV is below the low input display range limit. and sensor connection .. [Flashing]

8. INPUT RANGE TABLE

	Input type	Code		Input type	Code	Input type	Code		Input type	Code
к	0 to 100 °C 0 to 200 °C 0 to 400 °C 0 to 600 °C 0 to 800 °C	K A1 K A2 K A4 K A6 K A8	В,	1 50 to 1300 °C 1 50 to 1800 °C	B B3 B B8	R *1 0 to 600 °C *1 0 to 1000 °C *1 0 to 1300 °C *1 0 to 1750 °C	R A6 R A0 R B3 R B8		0.0 to 100.0 °C 0.0 to 200.0 °C 0.0 to 300.0 °C 0.0 to 400.0 °C 0.0 to 500.0 °C	D D1 D D2 D D3 D D4 D D5
	0 to 1000 °C 0 to 1300 °C 0 to 1350 °C	K A0 K B3 K B4	т	Input type 0 to 100 °C 0 to 200 °C 0 to 300 °C	CodeTA1TA2TA3	Input type 0 to 5VDC *3 -1999 to 9999 1 to 5VDC *3 -199.9 to 999.9 0 to 10VDC or	Code V 03 V 08 V 04	Pt100	0.0 to 600.0 °C -199.9 to +100.0 °C -199.9 to +200.0 °C -199.9 to +600.0 °C	D D6 D E1 D E2 D E6
	Input type	Code		0 to 400 °C	T A4	2 to 10VDC -19.99 to 99.99	V 09		-100.0 to +100.0 °C	D F1
J	0 to 100 °C 0 to 200 °C 0 to 300 °C	J A1 J A2 J A3				4 to 20mA *2 0 to 20mA *2	A 03 A 02		-50.0 to +200.0 °C -50.0 to +100.0 °C -50.0 to +200.0 °C	D G0 D G1 D G2
	0 to 400 ℃ 0 to 600 ℃ 0 to 800 ℃ 0 to 1000 ℃	J A4 J A6 J A8 J A0		Input type 0 to 100 °C 0 to 200 °C 0 to 300 °C	Code E A1 E A2 E A3	(*4) 0 to 400°C: Accurrentia	not que rente		•	
	Input type	Code	E	0 to 400 °C	E A4	(*1) 0 to 400 C: Accuracy is (*2)For the current input (0-	not guarante 20mA or 4-20	ea. 0mA) speci	fication, a resistor o	of 500Ω
*1 S *1 *1	0 to 1000 °C 0 to 1600 °C 0 to 1750 °C	S A0 S B6 S B8		0 to 600 °C 0 to 800 °C 0 to 1000 °C	E A6 E A8 E A0	must be connected b (*3)For (0-5VDC or 1-5VDC	etween the) input speci	input tern fication, mu	ninals. ust be custom made	9.

values manually. It is possible to happen when the set value is around the ambient temperature or is close to the maximum temperature achieved by the load.

Requirements for AT start

Start the autotuning when all following conditions are satisfied: (1) Prior to starting the AT function, end all the parameter settings other than PID.

(2) Confirm the LCK function has not been engaged.



When the autotuning is finished, the controller will automatically return to PID control.

Requirements for AT cancellation

The autotuning is canceled if any of the following conditions exist. (1) When the parameter "AT " value is changed."

- (2) When the power is turned off.
- (3) When powerfailure longer than 20ms occurs.

If the AT is canceled, the controller immediately changes to PID control. The PID values will be the same as before AT was activated.

When AT is completed, the controller immediately changes to PID control. If the control system does not allow the AT cycling process, set each PID constant manually to meet the needs of the application.



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